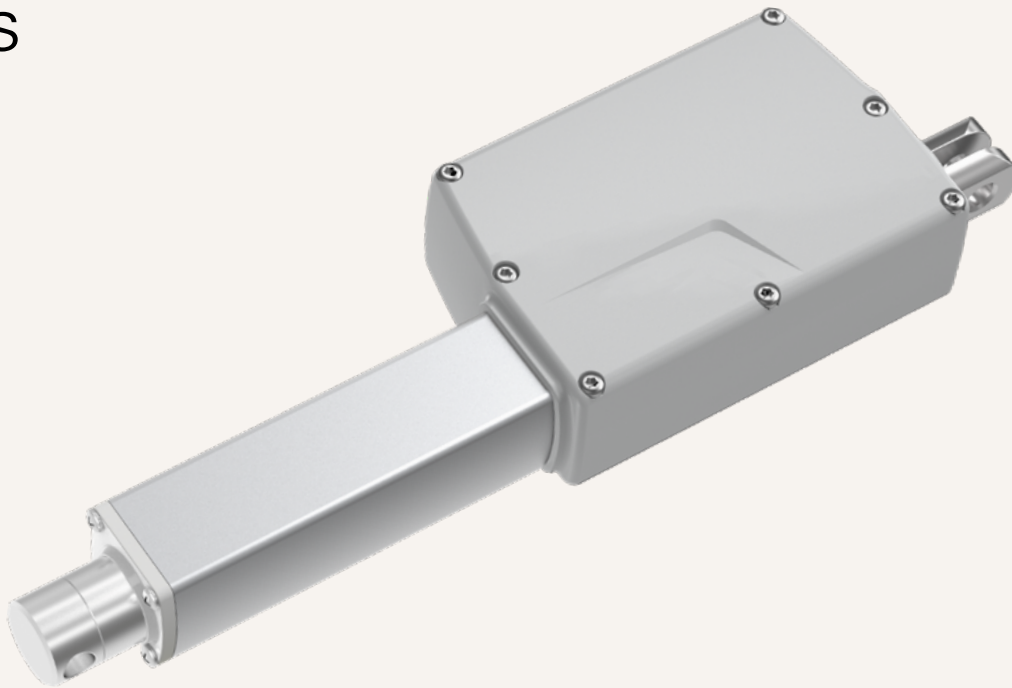


# TA29

series



## Product Segments

- **Care Motion**
- **Ergo Motion**

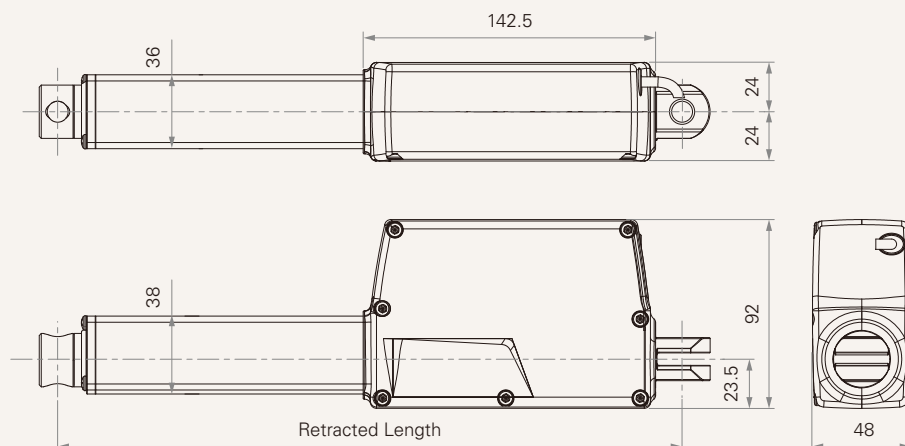
TiMOTION's TA29 is one of our new generation medical DC linear actuators, which can lift up to 6000N, yet has a small installation dimension. In addition to this, its IP rating is up to IP66W. The TA29 is highly recommended for various medical applications that require a short retracted length, yet need to support a large force, such as the leg adjustment or sling angle actuator on the patient hoist system.

### General Features

Max. load	6,000N (push); 3,500N (pull)
Max. speed at max. load	3mm/s
Max. speed at no load	30.2mm/s
Retracted length	≥ 178mm (depending on chosen options)
IP rating	IP66W
Stroke	25~600mm
Output signals	Hall sensors, POT
Voltage	12/24V DC; 12/24V DC (PTC)
Color	Black, grey
Operational temperature range	+5°C~+45°C
Suitable for patient hoist application	

## Drawing

Standard Dimensions  
(mm)



## Load and Speed

CODE	Load (N)		Self Locking Force (N)	Typical Current (A)		Typical Speed (mm/s)	
	Push	Pull		No Load 32V DC	With Load 24V DC	No Load 32V DC	With Load 24V DC
<b>Motor Speed (4800RPM, Duty Cycle 10%)</b>							
<b>B</b>	1500	1500	1500	1.5	5.0	30.2	17.7
<b>C</b>	2500	2500	2500	1.5	5.0	16.0	9.1
<b>D</b>	3500	3500	3500	1.5	5.0	10.9	6.5
<b>E</b>	4500	3500	4500	1.5	4.5	6.5	4.0
<b>P</b>	6000	3500	6000	1.5	4.5	5.5	3.0
<b>Motor Speed (5200RPM, Duty Cycle 10%)</b>							
<b>H</b>	1000	1000	1000	1.5	3.5	30.0	15.0
<b>K</b>	1500	1500	1500	1.5	3.5	20.0	10.0
<b>L</b>	2000	2000	2000	1.5	3.7	15.0	7.5
<b>M</b>	2500	2500	2500	1.5	3.7	10.0	5.0
<b>N</b>	4000	3500	4000	1.5	3.7	5.4	2.8

## Note

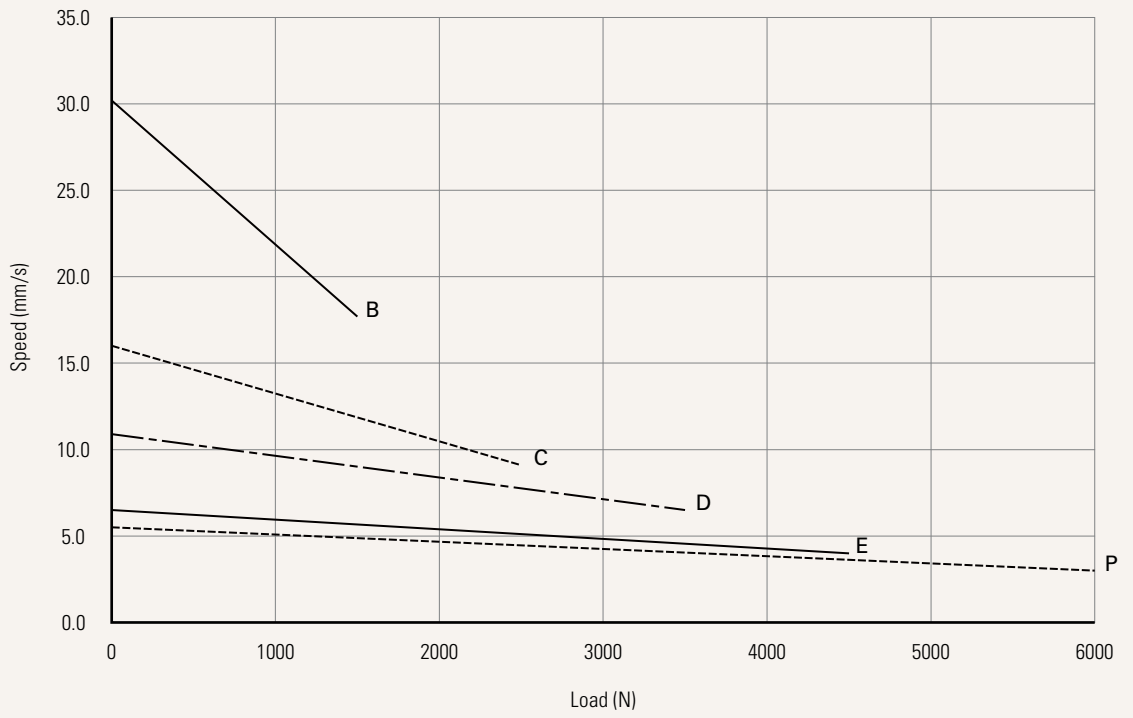
- 1 Please refer to the approved drawing for the final authentic value.
- 2 The current & speed in table are tested when the actuator is extending under push load.
- 3 This self-locking force level is reached only when a short circuit is applied on the terminals of the motor. All the TiMOTION control boxes have this feature built-in.
- 4 The current & speed in table are tested with 24V DC motor. With a 12V DC motor, the current is approximately twice the current measured in 24V DC; speed will be similar for both voltages.
- 5 The current & speed in table and diagram are tested with TiMOTION control boxes, and there will be around 10% tolerance depending on different models of the control box. (Under no load condition, the voltage is around 32V DC. At rated load, the voltage output will be around 24V DC)
- 6 Standard stroke: Min.  $\geq 25$ mm, Max. please refer to below table.

Load (N)	Max Stroke (mm)
<b>6000</b>	450
<b>3500 <math>\leq</math> load <math>\leq</math> 4500</b>	600
<b>&lt; 3500</b>	1000

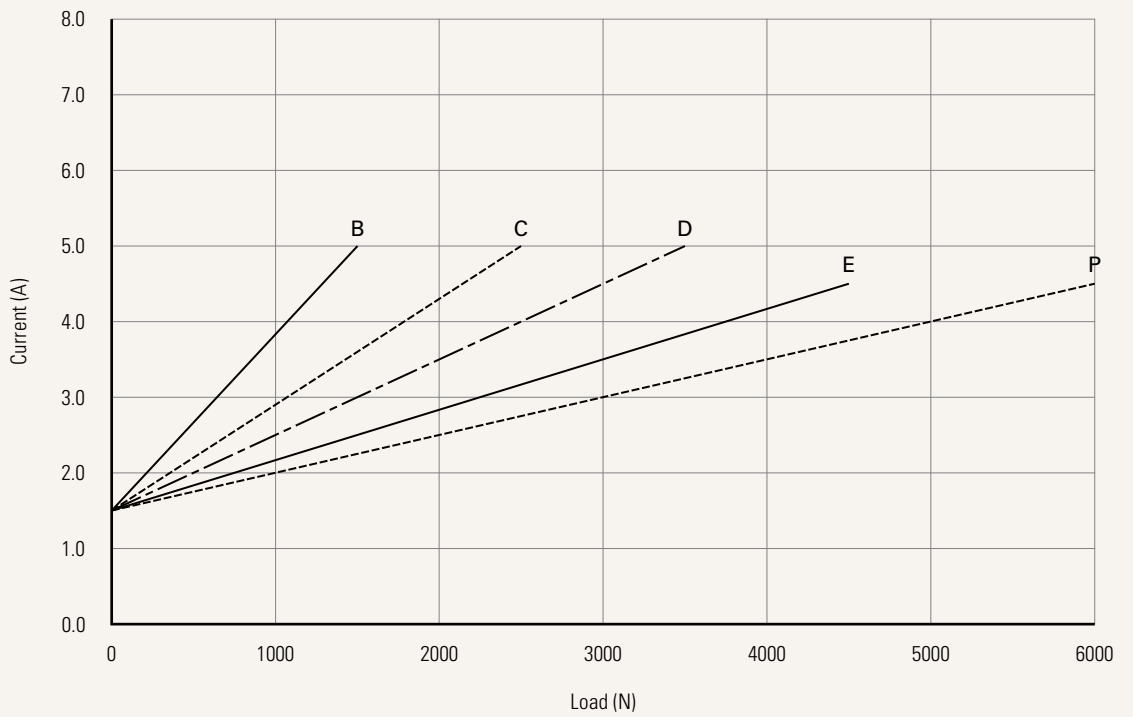
**Performance Data (24V DC Motor)**

Motor Speed (4800RPM, Duty Cycle 10%)

Speed vs. Load



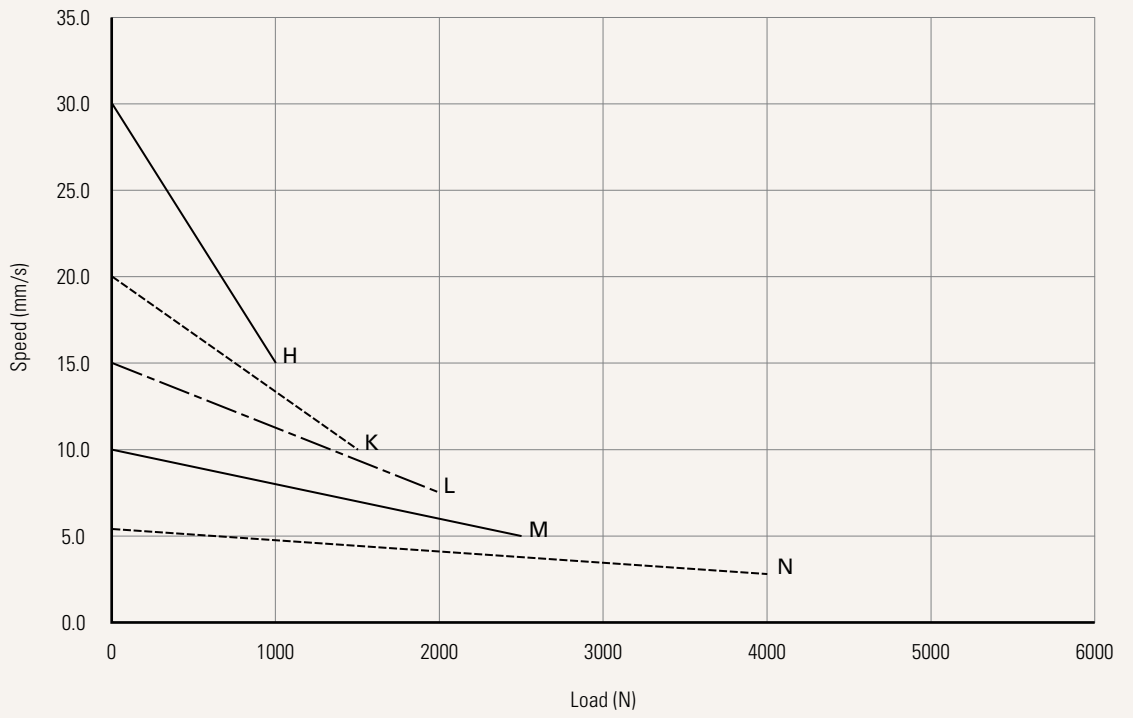
Current vs. Load



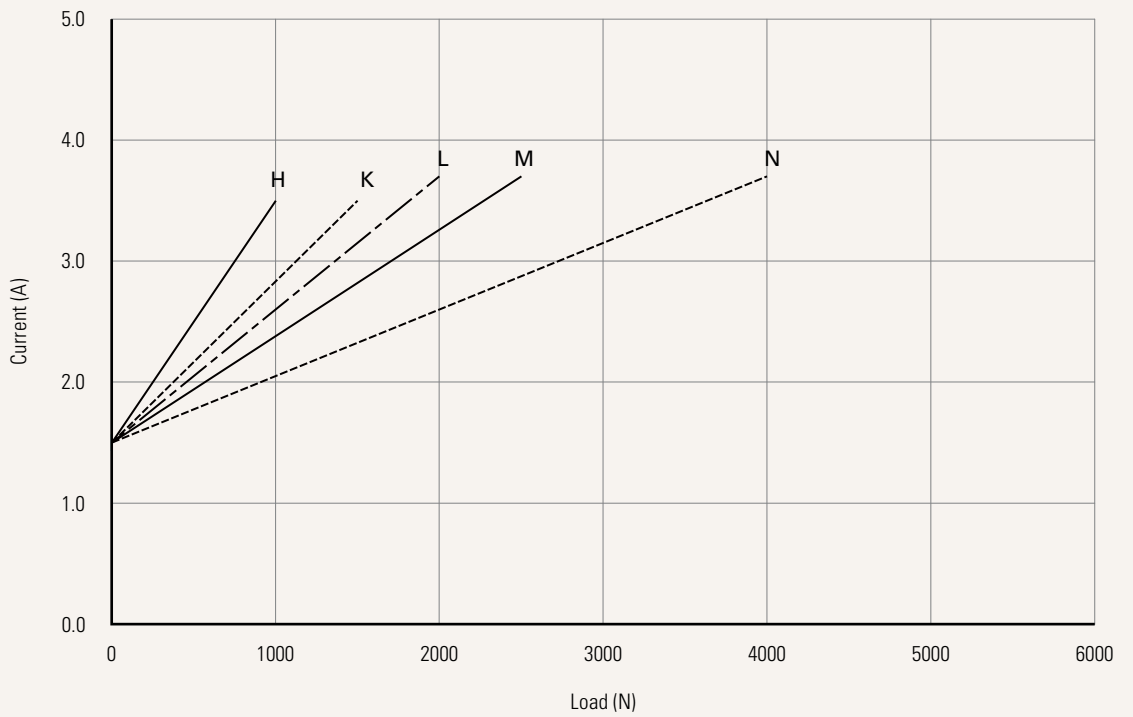
**Performance Data (24V DC Motor)**

Motor Speed (5200RPM, Duty Cycle 10%)

Speed vs. Load



Current vs. Load



<b>Voltage</b>	1 = 12V DC	2 = 24V DC	5 = 24V DC, PTC	6 = 12V DC, PTC
<b>Load and Speed</b>	<a href="#">See page 2</a>			
<b>Stroke (mm)</b>	<a href="#">See page 2</a>			
<b>Retracted Length (mm)</b>	<a href="#">See page 6</a>			
<b>Rear Attachment (mm)</b>	3 = Aluminum casting, U clevis, slot 6.2, depth 12.2, hole 10.2		4 = Aluminum casting, U clevis, slot 6.2, depth 12.2, hole 12.2	
	<a href="#">See page 7</a>			
<b>Front Attachment (mm)</b>	3 = Aluminum CNC, without slot, hole 10.2		4 = Aluminum CNC, without slot, hole 12.2	
	<a href="#">See page 7</a>			
<b>Direction of Rear Attachment (Counterclockwise)</b>	1 = 90°	2 = 0°		
	<a href="#">See page 7</a>			
<b>Color</b>	1 = Black	2 = Pantone 428C		
<b>IP Rating</b>	1 = Without	2 = IP54	3 = IP66	5 = IP66W
<b>Special Functions for Spindle Sub-Assembly</b>	0 = Without (Standard) 1 = Safety nut		2 = Standard push only 3 = Standard push only + safety nut	
<b>Functions for Limit Switches</b>	1 = Two switches at full retracted / extended positions to cut current 2 = Two switches at full retracted / extended positions to cut current + third one in between to send signal 3 = Two switches at full retracted / extended positions to send signal 4 = Two switches at full retracted / extended positions to send signal + third one in between to send signal 5 = Two switches at full retracted/extended positions to send signal (Operate with control box: TC1, TC8, TC10, TC14)			
	<a href="#">See page 8</a>			
<b>Output Signals</b>	0 = Without	2 = Hall sensor * 2	P = POT	
<b>Connector</b>	1 = DIN 6P, 90° plug 2 = Tinned leads 4 = Big 01P, plug C = Y cable (For direct cut system, water proof, anti pull)		E = Molex 8P, plug F = DIN 6P, 180° plug Q = Molex 6P, 90° plug	
	<a href="#">See page 8</a>			
<b>Cable Length (mm)</b>	0 = Straight, 100 1 = Straight, 500 2 = Straight, 750	3 = Straight, 1000 4 = Straight, 1250 5 = Straight, 1500	6 = Straight, 2000 7 = Curly, 200 8 = Curly, 400	B-H = For direct cut system <a href="#">See page 8</a>

## Retracted Length (mm)

1. Calculate  $A+B+C+D = Y$
2. Retracted length needs to  $\geq$  Stroke + Y
3. Retracted length needs to  $> 178\text{mm}$

### A. Front Attachment

<b>3, 4</b>	+115
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### B. Stroke (mm) Load (N)

	Load (N)				
	< 3500	3500	4000	4500	6000
<b>25~150</b>	-	+7	+7	+12	+27
<b>151~200</b>	+5	+15	+15	+20	+35
<b>201~250</b>	+5	+15	+15	+20	+35
<b>251~300</b>	+10	+20	+20	+25	+40
<b>301~350</b>	+10	+20	+20	+25	+40
<b>351~400</b>	+15	+25	+25	+30	+45
<b>401~450</b>	+20	+30	+30	+35	+50
<b>451~500</b>	+25	+35	+35	+40	+55
<b>501~550</b>	+30	+40	+40	+45	+60
<b>551~600</b>	+35	+45	+45	+50	+65

### C. Spindle Functions

	Load (N)				
	< 3500	3500	4000	4500	6000
<b>0</b>	-	-	-	-	-
<b>1</b>	+19	+12	+12	+12	+12
<b>2</b>	+6	+6	+6	+6	+6
<b>3</b>	+25	+18	+18	+18	+18

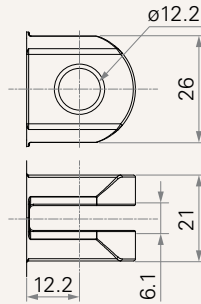
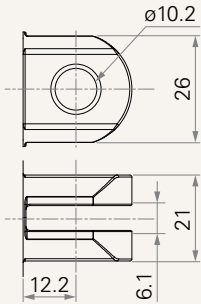
### D. Output Signals

<b>P_POT</b>	+20
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## Rear Attachment (mm)

3 = Aluminum casting, U clevis, slot 6.2, depth 12.2, hole 10.2

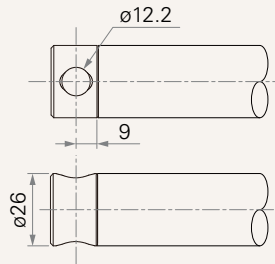
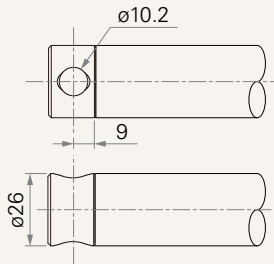
4 = Aluminum casting, U clevis, slot 6.2, depth 12.2, hole 12.2



## Front Attachment (mm)

3 = Aluminum CNC, without slot, hole 10.2

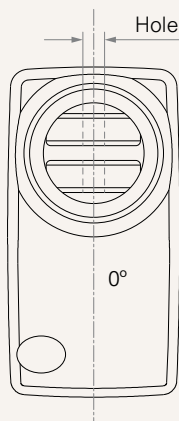
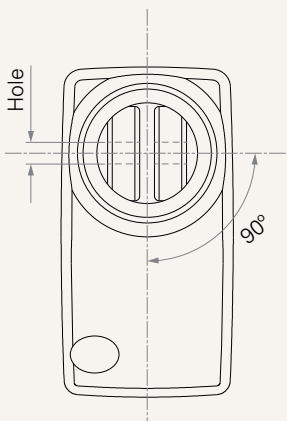
4 = Aluminum CNC, without slot, hole 12.2



## Direction of Rear Attachment (Counterclockwise)

1 = 90°

2 = 0°



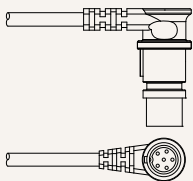
## Functions for Limit Switches

### Wire Definitions

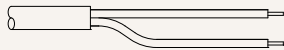
CODE	Pin					
	● 1 (Green)	● 2 (Red)	○ 3 (White)	● 4 (Black)	● 5 (Yellow)	● 6 (Blue)
1	extend (VDC+)	N/A	N/A	N/A	retract (VDC+)	N/A
2	extend (VDC+)	N/A	middle switch pin B	middle switch pin A	retract (VDC+)	N/A
3	extend (VDC+)	common	upper limit switch	N/A	retract (VDC+)	lower limit switch
4	extend (VDC+)	common	upper limit switch	medium limit switch	retract (VDC+)	lower limit switch
5	extend (VDC+)	N/A	upper limit switch	common	retract (VDC+)	lower limit switch

### Connector

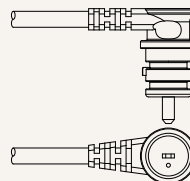
1 = DIN 6P, 90° plug



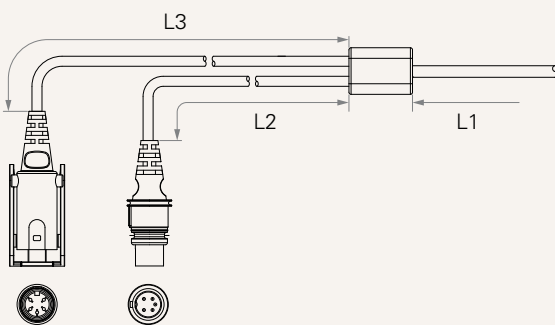
2 = Tinned leads



4 = Big 01P, plug



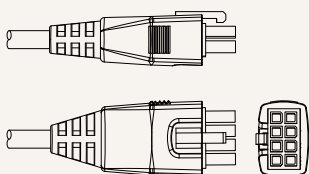
C = Y cable (for direct cut system, water proof, anti pull)



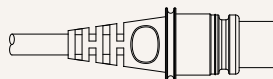
### Cable Length for Direct Cut System (mm)

CODE	L1	L2	L3
B	100	100	100
C	100	1000	400
D	100	2700	500
E	1000	100	100
F	100	600	1000
G	1500	1000	1000
H	100	100	1200

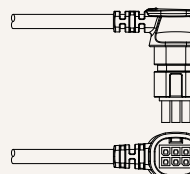
E = MOLEX 8P, plug



F = DIN 6P, 180° plug



Q = Molex 6P, 90° plug



### Terms of Use

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